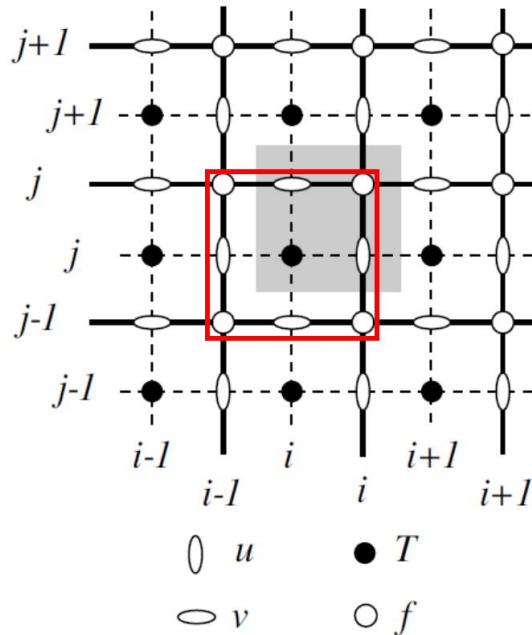


Rotating U and V components of velocity from model grid to a lat-lon grid

The figure below shows the Arakawa-C grid viewed from above. The solid thick lines delimit the grid cells. The indexing of the points is shown by the i and j 's. The grey shade includes the T-, u-, v- and f-points that have the same indexing (ie, $T(i, j), u(i, j), v(i, j), f(i, j)$).



To start using the velocities, you should move U and V velocities to the same point; T-point is ideal in case you want to use temperature and salinity as well (already located at T-points).

Let's look at the grid cell highlighted in red in the figure above. Note that:

- there is one u-point at each side of $T(i, j)$: $u(i - 1, j)$ and $u(i, j)$;
- and one v-point above and one below $T(i, j)$: $v(i, j)$ and $v(i, j - 1)$;

To move the U velocity component from the u-point (U_u) to a T-point (U_T), you should average the U's at each side of T; in this case:

$$U_T(i, j) = \frac{(U_u(i - 1, j) + U_u(i, j))}{2}$$

To move the V velocity component from the v-point (V_v) to a T-point (V_T), you should average the V's above and below T; in this case:

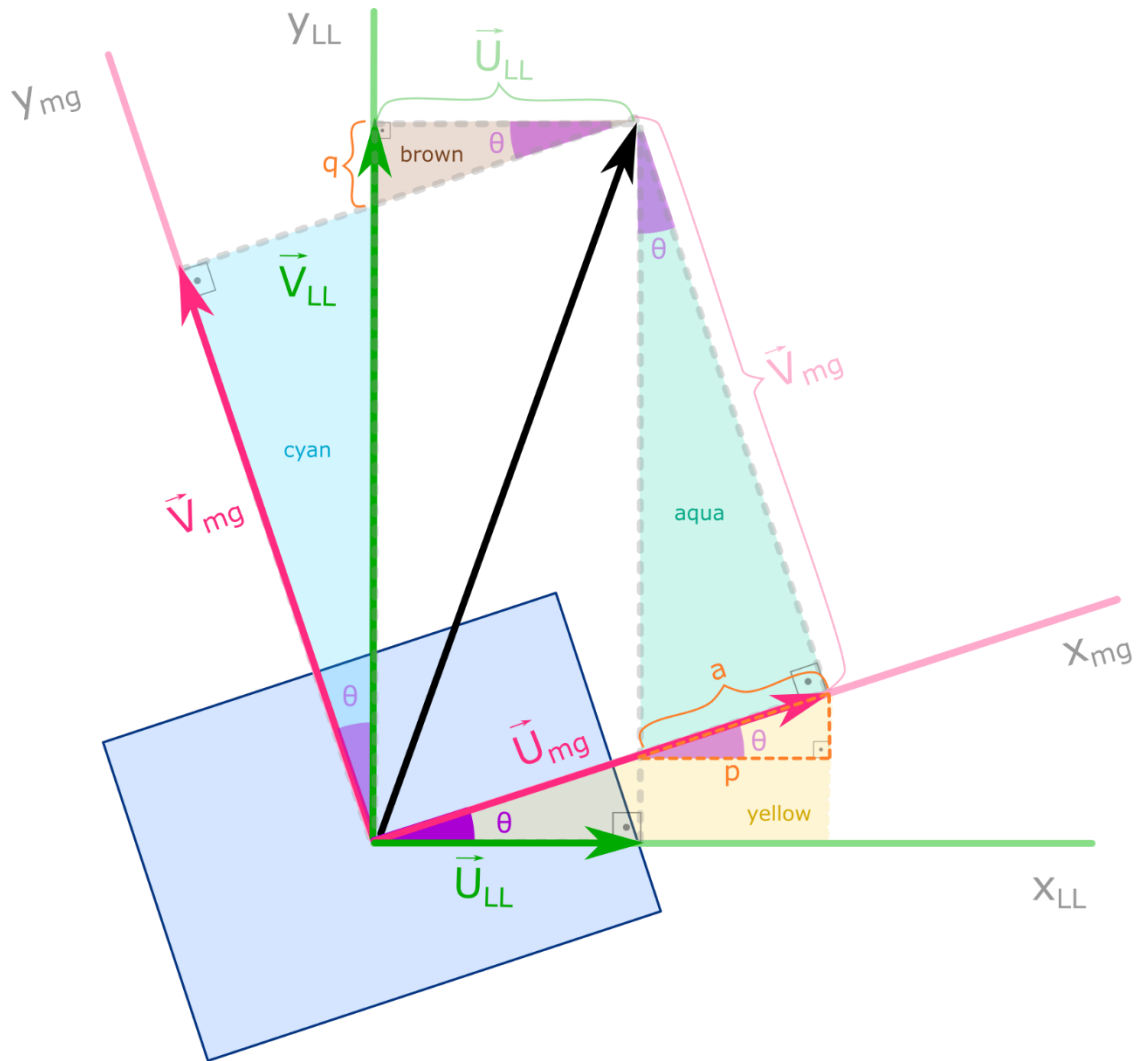
$$V_T(i, j) = \frac{(V_v(i, j) + V_v(i, j - 1))}{2}$$

Now that both components of the velocity are at the same point, we can rotate them. For clarity, we will now call U_T and V_T as \vec{U}_{mg} and \vec{V}_{mg} .

The figure below is a schematic of a model grid cell (in dark blue), the velocity vector in black, the model grid x and y orientation (x_{mg}, y_{mg} in magenta), U and V components of velocity in the model grid ($\vec{U}_{mg}, \vec{V}_{mg}$ in magenta), lat-lon grid orientation (x_{LL}, y_{LL} in green), rotated U and V components of the velocity ($\vec{U}_{LL}, \vec{V}_{LL}$ in green, what we want to find), and the angle θ between the model x (x_{mg}) and lat-lon x (x_{LL}), in dark purple.

Note that below we will only deal with the magnitude of the vectors, where

$$\begin{aligned} \vec{U}_{LL} &= U_{LL} \cdot \hat{i}_{LL} & \vec{V}_{LL} &= V_{LL} \cdot \hat{j}_{LL} \\ \vec{U}_{mg} &= U_{mg} \cdot \hat{i}_{mg} & \vec{V}_{mg} &= V_{mg} \cdot \hat{j}_{mg} \end{aligned}$$



First, let's find an expression for U_{LL} .

Looking at the yellow triangle, we can see that

$$\cos \theta = \frac{U_{LL} + p}{U_{mg}} \quad \text{or} \quad U_{LL} = U_{mg} \cdot \cos \theta - p \quad (1)$$

To find p we first look at the triangle delineated by the dashed orange lines. From this triangle, we see that

$$\cos \theta = \frac{p}{a} \quad \text{or} \quad p = a \cdot \cos \theta \quad (2)$$

From the aqua triangle,

$$\tan \theta = \frac{a}{V_{mg}} \quad \text{or} \quad a = V_{mg} \cdot \frac{\sin \theta}{\cos \theta} \quad (3)$$

Substituting (3) in (2),

$$p = V_{mg} \cdot \frac{\sin \theta}{\cos \theta} \cdot \cos \theta \quad \text{or} \quad p = V_{mg} \cdot \sin \theta \quad (4)$$

and (4) in (1)

$$U_{LL} = U_{mg} \cdot \cos \theta - V_{mg} \cdot \sin \theta \quad (5)$$

Great! Now let's find an expression for V_{LL} .

Looking at the cyan triangle,

$$\cos \theta = \frac{V_{mg}}{V_{LL} - q} \quad \text{or} \quad V_{LL} = \frac{V_{mg}}{\cos \theta} + q \quad (6)$$

Now, from the brown triangle,

$$\tan \theta = \frac{q}{U_{LL}} \quad \text{or} \quad q = U_{LL} \cdot \frac{\sin \theta}{\cos \theta} \quad (7)$$

Substituting the U_{LL} expression (5) into (7),

$$q = (U_{mg} \cdot \cos \theta - V_{mg} \cdot \sin \theta) \cdot \frac{\sin \theta}{\cos \theta}$$

$$q = U_{mg} \cdot \sin \theta - V_{mg} \cdot \frac{\sin^2 \theta}{\cos \theta} \quad (8)$$

Replacing (8) into (6), we have

$$V_{LL} = \frac{V_{mg}}{\cos \theta} + U_{mg} \cdot \sin \theta - V_{mg} \cdot \frac{\sin^2 \theta}{\cos \theta}$$

$$V_{LL} = V_{mg} \left(\frac{1 - \sin^2 \theta}{\cos \theta} \right) + U_{mg} \cdot \sin \theta$$

We know that $\sin^2 \theta + \cos^2 \theta = 1$, so replacing $1 - \sin^2 \theta$ by $\cos^2 \theta$, we finally get

$$V_{LL} = V_{mg} \cdot \cos \theta + U_{mg} \cdot \sin \theta \quad (9)$$